

Ch4. One parameter subgroups and the exponential map.

Definition. (1) **(Matrix) Lie group** is a closed subgroup G of $GL(n, \mathbb{R})$. i.e., G is a subgroup of $GL(n, \mathbb{R})$ and satisfies the following condition: If a sequence of matrices $\{A_k\} \subset G$ converges in $GL(n, \mathbb{R})$, then $\lim_{k \rightarrow \infty} A_k \in G$. (Use $G < GL(n, \mathbb{R})$ to denote that G is a matrix Lie group.)

Since $L(G)$ is defined as the collection of derivatives of smooth curves in G , one may ask how many different smooth curves we actually need to describe it. To answer this question, we will study one-parameter subgroups and the matrix exponential today.

In this lecture, I will assume that G is a Lie gp without further mention.

Recall (G) Lie gp.

$$L(G) := T_I G = \{ \gamma'(0) \mid \gamma: \mathbb{R} \rightarrow G \text{ smooth} \ \& \ \gamma(0) = I \}$$

How many curves we need? to specify $T_I G$

- Goal
- learn one parameter subgroup
 - learn matrix exponential.
 - specify $L(G)$
 - $\det(e^A) = e^{\text{tr}(A)}$

4.1 One-parameter subgroups

$$L(G) = \{ A \in M(n, \mathbb{R}) \mid e^{tA} \in G \text{ for } \forall t \in \mathbb{R} \}$$

Def A map $\gamma: \mathbb{R} \rightarrow G \subset GL(n, \mathbb{R})$ is called a "one-parameter subgroup of G " if γ is a continuous group homomorphism

Prob 4.1.1 (c) $\gamma(t) = \begin{pmatrix} e^t & 0 \\ 0 & e^{-t} \end{pmatrix} \in M(n, \mathbb{R})$ $\gamma: \mathbb{R} \rightarrow M(n, \mathbb{R})$

$\gamma(t+s) = \begin{pmatrix} e^{t+s} & 0 \\ 0 & e^{-(t+s)} \end{pmatrix} = \begin{pmatrix} e^t e^s & 0 \\ 0 & e^{-t} e^{-s} \end{pmatrix} = \begin{pmatrix} e^t & 0 \\ 0 & e^{-t} \end{pmatrix} \begin{pmatrix} e^s & 0 \\ 0 & e^{-s} \end{pmatrix} = \gamma(t) \gamma(s)$

$\text{① } \det \gamma(t) = 1$

$\gamma: \mathbb{R} \rightarrow GL(n, \mathbb{R})$ conti. homo.

4.2 The exponential map in dimension 1.

Note $GL(1, \mathbb{R}) \approx \mathbb{R} \setminus \{0\}$

$$|a| \leftrightarrow a$$

$$GL(1, \mathbb{R}) \approx \mathbb{R} \setminus \{0\}$$

Prob 4.2.2

(1) If $\gamma : \mathbb{R} \rightarrow GL(1, \mathbb{R})$: one-para. subgp,

then $\gamma(t) = e^{at}$ for $\forall t \in \mathbb{R}$.

PF with $\gamma : \mathbb{R} \rightarrow \mathbb{R} \setminus \{0\}$. Assume $\gamma : \mathbb{R} \rightarrow GL(1, \mathbb{R}) = \mathbb{R} \setminus \{0\}$ is a one-parameter subgroup of $GL(1, \mathbb{R})$ and set $\gamma(1) = b > 0$ ($b > 0$ is because homomorphism maps identity to identity; $\gamma(0) = 1$ and γ is continuous $\gamma(0)$ and $\gamma(1)$ have the same sign by the intermediate value theorem).

- (1) For each $a \in \mathbb{R}$, $\gamma(ma) = \gamma(a + \dots + a) = \gamma(a) \cdots \gamma(a) = (\gamma(a))^m$ for all positive integer m .
- (2) Using the result in (1), $\gamma(m) = b^m$ for all positive integer m .
- (3) Use $\gamma(m)\gamma(-m) = \gamma(m + (-m)) = \gamma(0) = I_1 = 1$ to show that $\gamma(-m) = (\gamma(m))^{-1} = b^{-m}$ for all positive integer m .
- (4) For any $n, m \in \mathbb{N}$, since $n/m > 0$, $\gamma(n/m) > 0$ by continuity and the intermediate value theorem. Then,

$$b^n = \gamma(n) = \gamma\left(m \cdot \frac{n}{m}\right) = \left(\gamma\left(\frac{n}{m}\right)\right)^m \implies \gamma\left(\frac{n}{m}\right) = b^{\frac{n}{m}}.$$

Combining this with (3), we have $\gamma(t) = b^t$ for all $t \in \mathbb{Q}$.

- (5) Since γ is continuous, for each $t \in \mathbb{R}$, we can take a sequence of rational numbers $\{r_n\}$ such that $r_n \rightarrow t$ as $n \rightarrow \infty$. Then,

$$\gamma(t) = \gamma\left(\lim_{n \rightarrow \infty} r_n\right) = \lim_{n \rightarrow \infty} \gamma(r_n) = \lim_{n \rightarrow \infty} b^{r_n} = b^t.$$

- (6) Finally, set $a = \log b \in \mathbb{R}$, then we have

$$\gamma(t) = b^t = e^{(\log b)t} = e^{at},$$

and since $\gamma(t)$ is smooth and $\gamma(0) = I_1$, we have $\gamma'(0) = a \in L(G)$.

$\gamma(t) = e^{tA}$
(2) If $\gamma : \mathbb{R} \rightarrow GL(n, \mathbb{R})$: one-para. subgp,
then $\gamma(t) = e^{tA}$ for $\forall t \in \mathbb{R}$.

General

If make sense to multiply a matrix A by a scalar t ,
but what does it mean e^{matrix} ?

4.3. Calculating the matrix exponential

Note $e^x = \sum_{k=0}^{\infty} \frac{x^k}{k!}$

Def $\exp: M(n, \mathbb{R}) \rightarrow GL(n, \mathbb{R})$ is defined by

a series

$$\exp(A) = e^A = \sum_{k=0}^{\infty} \frac{1}{k!} A^k =: \frac{A^k}{k!}$$

Prmk e^A is well-defined for every $A \in M(n, \mathbb{R})$.

pf) Let $\|\cdot\|$ a norm on $M(n, \mathbb{R})$ as

$$\|A\| = n \cdot \max_{i,j} |A_{ij}| \quad \text{where } A = [A_{ij}] \in M(n, \mathbb{R}).$$

Using $\|BC\| \leq \|B\| \cdot \|C\|$

$$\sum_{k=0}^{\infty} \left\| \frac{A^k}{k!} \right\| = \sum_{k=0}^{\infty} \frac{\|A\|^k}{k!} \Rightarrow e^{\|A\|} < \infty.$$

$$\begin{aligned} \|BC\| &:= n \cdot \max_{i,j} \left| \sum_k b_{ik} c_{kj} \right| \\ &\leq n \cdot \sum_{k=0}^n \frac{\|B\|}{n} \cdot \frac{\|C\|}{n} \\ &= \|B\| \|C\| \end{aligned}$$

real exp.

Prob 4.3.1 Let $A = \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix}$. Find e^{tA}

- Find e^{tA}
- $\gamma'(0) = A$
- $\det(e^{tA}) = e^{\text{tr}(tA)}$

$$tA = \begin{bmatrix} 0 & t \\ 0 & 0 \end{bmatrix}, \quad (tA)^k = \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix}, \quad k \geq 2$$

$$e^{tA} = I + tA + \frac{(tA)^2}{2!} + \dots = \begin{bmatrix} 1 & t \\ 0 & 1 \end{bmatrix}.$$

$$\det(e^{tA}) = |x| = e^{0+0} = e^{\text{tr}(tA)}.$$

4.4 Properties of the matrix exponential

Proposition 4.1 (Algebraic properties of the exponential function). Let $A, B \in M(n, \mathbb{R})$.

- (1) $\exp(O_n) = I_n$. $e^{O_n} = I_n$
- (2) If $AB = BA$, then $\exp(A+B) = \exp(A)\exp(B)$. $e^{A+B} = e^A \cdot e^B$
- (3) For any $A \in M(n, \mathbb{R})$, $\exp(A)$ is invertible and $(\exp(A))^{-1} = \exp(-A)$. $(e^A)^{-1} = e^{-A}$
- (4) For any $A \in M(n, \mathbb{R})$, $\exp(A^T) = (\exp(A))^T$. $(e^A)^T = e^{A^T}$
- (5) For any $A \in M(n, \mathbb{R})$, $P \in GL(n, \mathbb{R})$, $\exp(PAP^{-1}) = P \exp(A) P^{-1}$. $e^{PAP^{-1}} = P e^A P^{-1}$

Proof. The proof is basic but somewhat lengthy calculations, I'll omit the details here. □

$$e^A := \sum_{k=0}^{\infty} \frac{A^k}{k!}$$

$$[e^{tA}]_{ij} = \sum_{k=0}^{\infty} \frac{[A^k]_{ij} t^k}{k!}$$

Using the fact that e^A : abs. conv

$$\therefore \frac{d}{dt} e^{tA} \stackrel{*}{=} \frac{d}{dt} \sum_{k=0}^{\infty} \frac{(tA)^k}{k!}$$

diff. term by term. $= \sum_{k=0}^{\infty} \frac{k t^{k-1} A^k}{k!} = A e^{tA}$

$$|[A^k]_{ij}| \leq \frac{\|A\|^k}{n}$$

$$\therefore \gamma(t) = e^{tA} \rightarrow \gamma'(t) = A\gamma(t)$$

$$\text{ODE } \begin{cases} \gamma'(t) = A\gamma(t) \\ \gamma(0) = \gamma_0 \end{cases} \xrightarrow{\text{sol}} \gamma(t) = e^{tA} \cdot \gamma_0$$

Prob 4.4.4

① $e^{0_n} = I_n$

② $e^A \in GL(n, \mathbb{R})$ for $\forall A \in M(n, \mathbb{R})$.

③ $e^{(t+s)A} = e^{tA} \cdot e^{sA}$

Pf) $e^{0_n} = I_n + 0_n + \dots = I_n$. (by def)

$e^A \cdot e^{-A} = e^{A-A} = e^{0_n} = I_n$
↑
 $A, -A$: commute.

$\therefore \gamma(t) = e^{tA}$ is
a one-parameter
subgp of $GL(n, \mathbb{R})$
& smooth, $\gamma(0) = I_n$
 $\therefore A \in L(G)$.

$L(GL(n, \mathbb{R})) \stackrel{\circ}{=} M(n, \mathbb{R})$.
= by def.

P.4.3.3

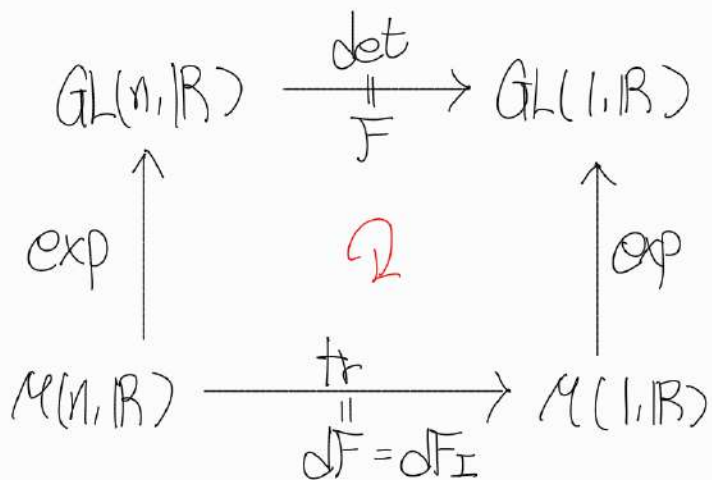
$A = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}$

$\gamma(t) = e^{tA} = \begin{bmatrix} \cos t & -\sin t \\ \sin t & \cos t \end{bmatrix}$

$\gamma(0) = \gamma(2\pi)$

4.5 Using exp to determine L(G).

We will prove a very useful theorem $\det(e^A) = e^{\text{tr}(A)}$.
 It can be expressed the following commutative diagram.



Examples ① $A = \text{diag}(a_1, \dots, a_n)$ $A^k = \text{diag}(a_1^k, \dots, a_n^k)$

$$e^A: \text{diag} \ \& \ [e^A]_{ii} = \sum_{k=0}^{\infty} \frac{[A^k]_{ii}}{k!} = a_i^k = e^{a_i}$$

Proof. (1) For diagonal matrix $A = \text{diag}(a_1, \dots, a_n)$, we have

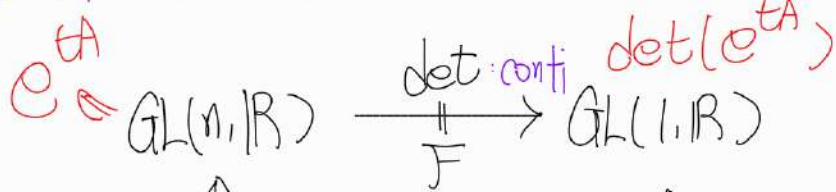
$$e^A = \text{diag}(e^{a_1}, \dots, e^{a_n}) \implies \det(e^A) = e^{a_1} \dots e^{a_n} = e^{\text{tr}(A)}.$$

② A:

For a diagonalizable matrix $A = PDP^{-1}$, where D is a diagonal matrix and $P \in GL(n, \mathbb{R})$, we have

$$\det(e^A) = \det(e^{PDP^{-1}}) = \det(Pe^D P^{-1}) = \det(e^D) = e^{\text{tr}(D)} = e^{\text{tr}(A)}.$$

③ $A \in M(n, \mathbb{R})$



set $\gamma(t) = \det(e^{tA})$

- $\gamma: \mathbb{R} \rightarrow GL(n, \mathbb{R})$ well-def.
- $\gamma: \text{conti}$ (exp, det: conti)
- $\gamma(t+s) = \det(e^{(t+s)A})$
- $= \det(e^{tA} \cdot e^{sA})$
- $(\because (tA)(sA) = (sA)(tA))$
- $= \det(e^{tA}) \det(e^{sA})$
- $= \gamma(t) \gamma(s)$

$t \in \mathbb{R}, A \in M(n, \mathbb{R})$

$\therefore \gamma(t)$ is a one-parameter subgroup of $GL(n, \mathbb{R})$

$$\gamma(t) = e^{bt} \text{ for some } b \in \mathbb{R}. \text{ (by Prob. 4.2.2)}$$

$$F = \det, \quad \gamma(t) = F(e^{tA}) = e^{bt} \quad \forall t \in \mathbb{R}$$

$$\xrightarrow{\text{diff}} \frac{d}{dt} \Big|_{t=0} F(e^{tA}) = dF \left(\frac{d}{dt} \Big|_{t=0} e^{tA} \right) = dF(A) = \text{tr}(A)$$

$$\frac{d}{dt} \Big|_{t=0} e^{bt} = b \quad \therefore \det(e^A) = e^b = e^{\text{tr}(A)}$$

$e^{0A} = I_n$ & smooth *A*

Most important thm.

Thm 4.4 G : Lie subgroup of $GL(n, \mathbb{R})$, $L(G) = T_{I_n}G$.

Then, $A \in L(G) \Rightarrow e^A \in G$.

ie. $L(G) = \{ A \in M(n, \mathbb{R}) \mid e^{tA} \in G \text{ for } \forall t \in \mathbb{R} \}$

Not prove " just examples.

$\circ G = O(n, \mathbb{R}) : \forall A \in L(G) = \{ A \in M(n, \mathbb{R}) : A^T = -A \}$

For a smooth curve $\gamma: \mathbb{R} \rightarrow G$ st.

$$\gamma(0) = I_n, \quad \gamma'(0) = A,$$

$$\gamma(t)^T \gamma(t) = I \xrightarrow{d/dt} \gamma'(t)^T \gamma(t) + \gamma(t)^T \gamma'(t) = 0$$

$$\xrightarrow{t=0} A^T I + I^T A = 0 \quad \therefore A^T = -A.$$

$$\Rightarrow \det(e^A) = \det I$$

Remark. By using the geometric series:

$$\sum_{k=0}^{\infty} x^k = \frac{1}{1-x}, \quad |x| < 1,$$

we can find the Taylor series of $\log(1+x)$ at $x=0$ as follows:

$$\log(1+x) = \int_0^x \frac{1}{1+t} dt = \int_0^x \sum_{k=0}^{\infty} (-1)^k t^k dt = \sum_{k=0}^{\infty} (-1)^k \frac{x^{k+1}}{k+1} = x - \frac{x^2}{2} + \frac{x^3}{3} - \frac{x^4}{4} + \dots, \quad |x| < 1.$$

Then,

$$\log(x) = \log(1+(x-1)) = (x-1) - \frac{1}{2}(x-1)^2 + \frac{1}{3}(x-1)^3 - \frac{1}{4}(x-1)^4 + \dots, \quad |x-1| < 1.$$

Definition. For $M \in GL(n, \mathbb{R})$, the natural **logarithm** of M is defined as

$$\log(M) := (M - I_n) - \frac{1}{2}(M - I_n)^2 + \frac{1}{3}(M - I_n)^3 - \frac{1}{4}(M - I_n)^4 + \dots = \sum_{k=1}^{\infty} \frac{(-1)^{k+1}}{k} (M - I_n)^k,$$

provided that $\|M - I_n\| < 1$ (using $\|(M - I_n)^m\| \leq \|M - I_n\|^m$, we can show if $\|M - I_n\| < 1$, the matrix-valued series will converge)

Proposition 4.8 (Properties of the logarithm function). For $M \in GL(n, \mathbb{R})$ and $A \in M(n, \mathbb{R})$, we have the following:

- (1) The series for $\log(M)$ converges for $\|M - I_n\| < 1$.
- (2) When A is near O_n , $\log(e^A) = A$. And when M is near I_n , $e^{\log(M)} = M$.
- (3) If M_1 and M_2 are near I_n and $\log(M_1)$ and $\log(M_2)$ commute, then

$$\log(M_1 M_2) = \log(M_1) + \log(M_2).$$

Proof. (3) Since M_1 and M_2 are near I_n , we can write

$$X = \log(M_1), \quad Y = \log(M_2),$$

where X and Y are near O_n . Since X and Y commute, by Prop4.1(2),

$$M_1 M_2 = e^X e^Y = e^{X+Y}.$$

Since exp is invertible, and therefore one-to-one near $O_n \in M(n, \mathbb{R})$,

$$\log(M_1 M_2) = \log(e^{X+Y}) = X + Y = \log(M_1) + \log(M_2).$$

□